

# Prognosis Deflection of Bridge: Evaluation Methods for Quality Prediction of Coupled Partial Models

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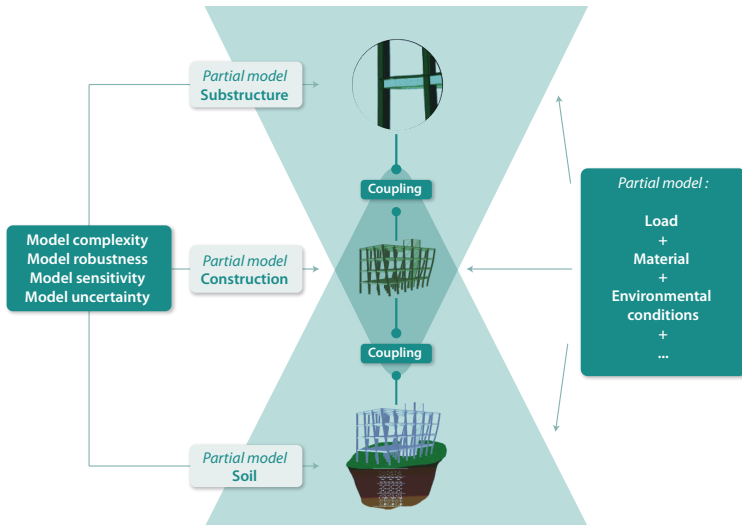
Bauhaus-Universität Weimar

Research Training Group 1462

Nepal Engineers' Association „Friday Talk”, Kathmandu  
February 10<sup>th</sup>, 2017

supported by the German Research Foundation 

# System of Coupled Partial Models



# Why Evaluating Quality of Models?

## Phenomenon creep: several models exist

- Purely empirical models: GL2000
- Semi-empirical: MC10, ACI209
- Mostly physically based: B3
- Rheological models: Bockhold, Heidolf
- .....

## Which model to choose?

*„As simple as possible, but not simpler?“*

Albert Einstein

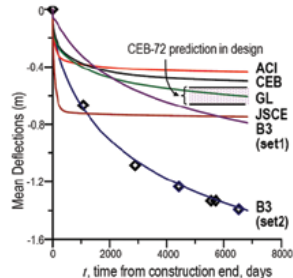
# Example of Poor Quality [Bažant 2010]

## Collapse of Koror-Babeldaob Bridge in Palau

- Strong underestimation of creep influence - inappropriate model
- Failure due to creep deformation and resulting loss of pretensioning



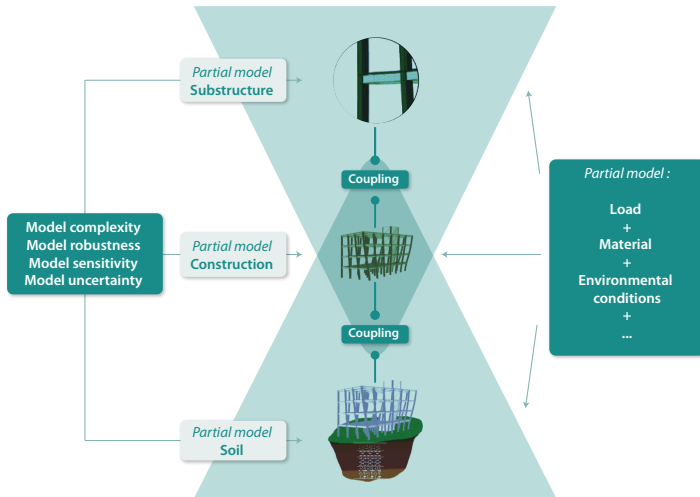
Bridge failure



Prognosis of displacements for different creep models



# System of Coupled Partial Models



Coupling necessary? (Different Softwares, models, scales, ...)

# Contents

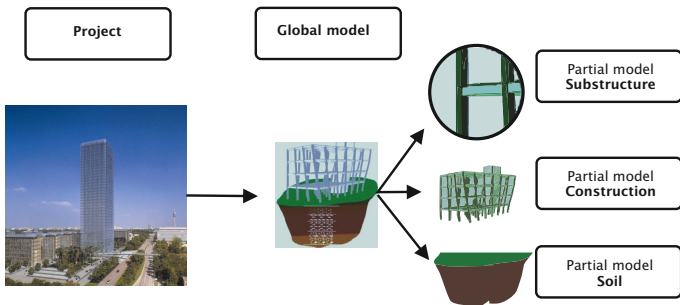
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- 3 Modeling Techniques
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- 6 Global Model
- 7 Conclusions

# Definition of Models

## Models...

- ... should describe events in the physical world, deflection of a structure, social developments
- ... are an abstraction from reality; never describe everything
- ... are designed for specific purposes
- ... often include simplifications
- ... are related to specific phenomena → partial models

# From Reality to Global and Partial Models



The global model  $GM$  is the representation of the conceptual model (observed system, event). The underlying behavior of a phenomenon can be investigated more detailed, comprehensible, and comparable for a specific question. As a consequence, a global model of a structure consists in general of several partial models  $PM_i$ .

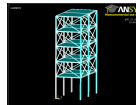
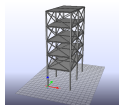
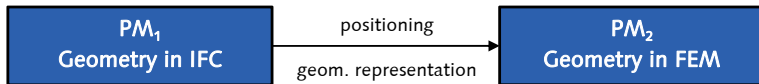
# Ways for decomposition of a global model

- regarding multidisciplinary  
e.g. for example multi-physics concerning electricity and magnetism
- a functional differentiation  
e.g. substructure, superstructure, foundation, soil . . .
- the spatial alignment of the models  
e.g. columns, beams, frames, . . .
- the physical meaning of the components  
e.g. material law, kinematic equations, . . .

# Coupling - Unidirectional

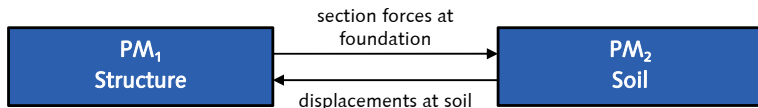
## Definition of partial models coupling

- Coupling is the process of transferring the information from one partial model  $PM_i$  to another.
- Unidirectional coupling: exchange of data is allowed only one way; output of  $PM_i$  depends independent from  $PM_{i+1}$
- Unidirectional: cannot describe iterative and interactive events



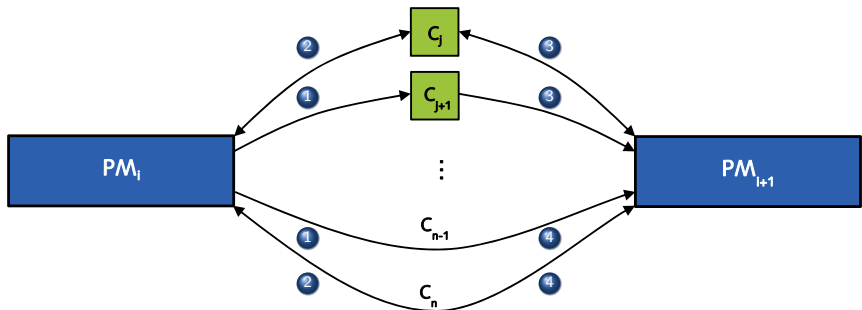
# Bidirectional Coupling

- Exchange of data is allowed both-way
- Output of  $PM_i$  and/or  $PM_{i+1}$  affect each other
- Can be used to compute iterative and interactive facts, iteration steps are necessary to reach equilibrium condition in the coupling



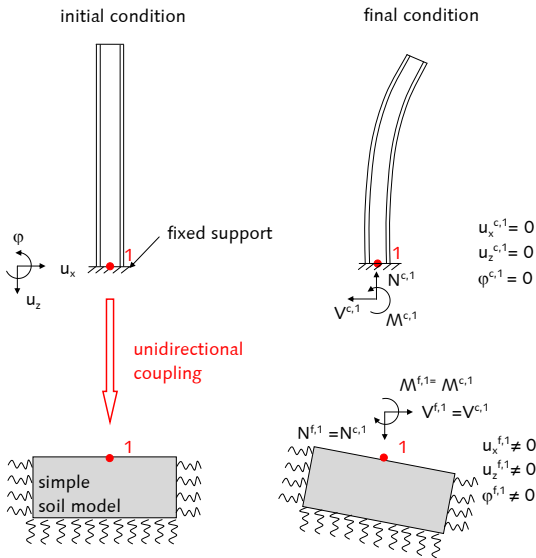
# General Coupling Representation

- ① unidirectional
- ② bidirectional
- ③ via an additional partial model
- ④ via boundary conditions

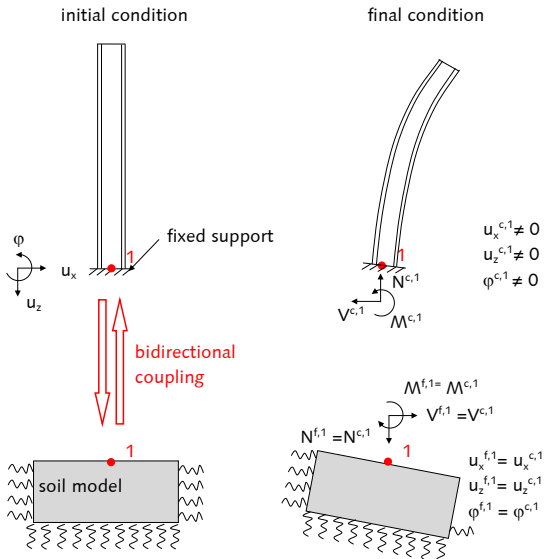




# Example: Coupling Column-Foundation



# Example: Coupling Column-Foundation

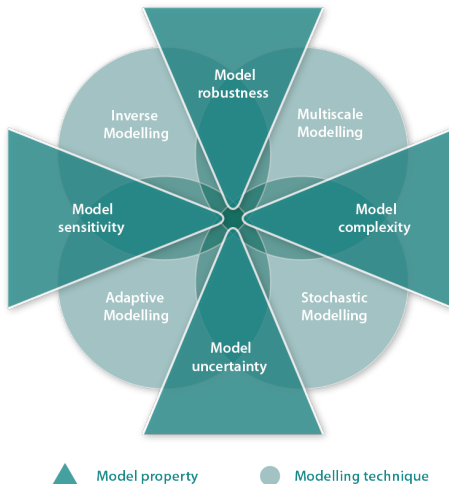


# Challenges for Evaluation of Coupling

## Important Questions

- Do we already have adequate models for certain or all parts of the physical event under consideration?
- Does it make sense to decompose the event into several conceptual models?
- Is a coupling physically justified?
- Do we have a certain overlap of the model domains?
- What are the input and output parameters that have to be coupled and how can we do so?

# Techniques



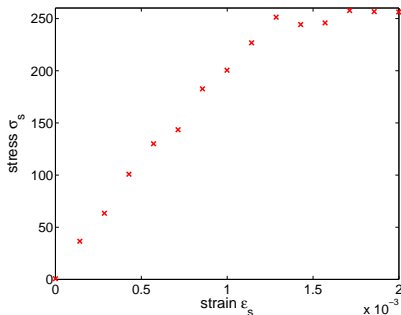
# Inverse Modeling

What is Inverse modeling?

Parameters are determined from measurements of model components

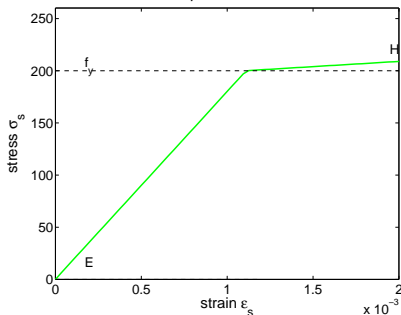
# Inverse Modeling - Example

Measured stress-strain-relation



Measurements

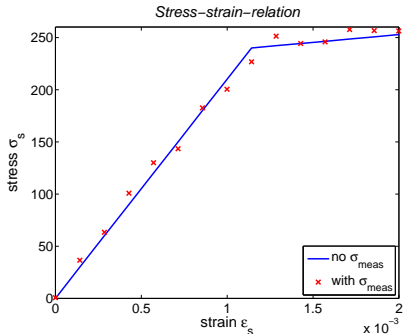
Model to predict stress-strain



Model

What are the model parameters  $E$ ,  $f_y$ , and  $H$  for an optimal fit?

# Inverse Modeling - Example



Optimal fit to the measurements

# Inverse Modeling

## Problems

- Existence
- Uniqueness
- Data dependency of parameters
- Measurements are sparse, incomplete, with errors

## Inverse modeling techniques

- Calibration
- System identification
- Regularization techniques
- Bayesian Updating



# Stochastic Modeling

## Stochastic modeling techniques

- Statistical description of input parameters
- Stochastic Finite Elements

## Application in civil engineering

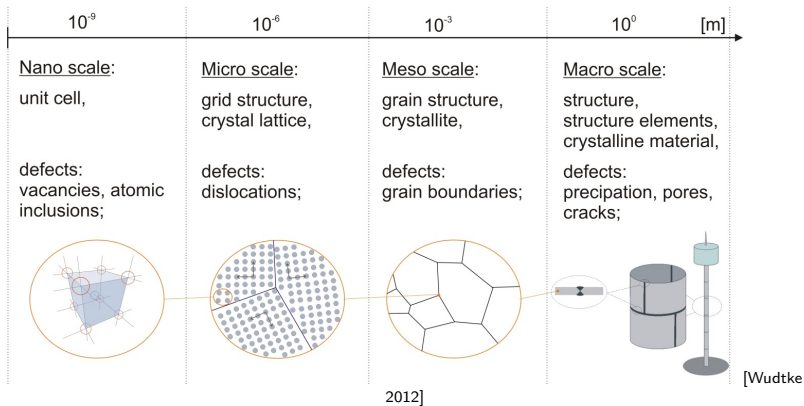
- Reliability analysis
- Tool to quantify model quality

## Examples of techniques to improve computational performance

- Response Surface Methods
- Latin Hypercube Sampling

# Multiscale Modeling

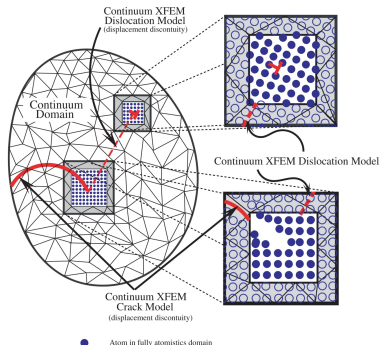
Simulates structures' behavior over different spatial-temporal scales



# Concurrent Multiscale Modeling

## Techniques to do it

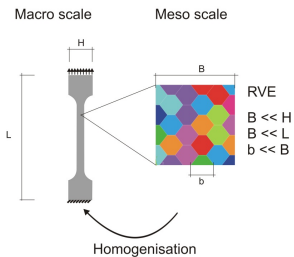
- Important subdomains are modeled extensively
- The rest of the domain is just coarsely approximated



[Ghorashi2012]

# Hierarchical Multiscale Modeling

- Idea: Different scales are modeled and the finer scaled parameter results are translated to the upper scale
- Reference Volume Element to gain a representative model
- Homogenization methods to relate different scales
- Application: integrated computational materials engineering; knowledge at finer scale is used at coarser scale



[Wudtke2012]

# Adaptive Modeling

For what it is used for?

To reduce and control numerical or model errors

How does it works?

By modifying...

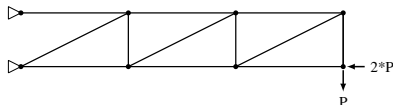
- **Model**
- Mesh
- Order of approximation
- Time steps
- Other numerical algorithm features

... depending on a specified error limit using error estimators

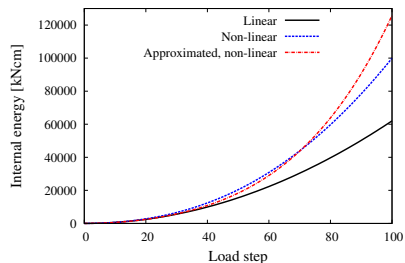
# Adaptive Modeling - Example

## Adaptivity for geometric non-linear kinematics [Nikulla2012]

- Error estimation of geometric linear models
- Results of first load steps were used to estimate error for larger load steps
- In case of large error switch to non-linear model



Geometry and loading of truss element



Internal energy of system depending on load step

# Model Properties

## Main model properties

- Complexity
- Uncertainty
- Reliability
- Sensitivity
- Robustness
- Risk

# What is Complexity?

## *Complexus*

= Twisted together, Embraced, Entwined, ...

The definition implies that for a complex...

- At least two parts are required.
- The parts should be connected together in a way that it is difficult to separate them.

There comes the difficulty!

A composite structure of distinct but connected parts where the response of one part affects the response of the other parts



# How to measure complexity?

## Not a general measure yet...

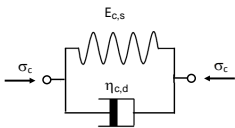
Although many measures of complexity are available for different scientific contexts, no measure is yet proposed that could be applied to a wide range of systems.

## There are still some hopes!

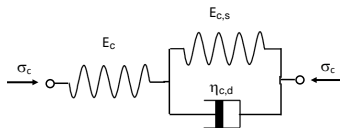
We consider a system as more complex than the other if...

- more components can be distinguished  
or
- more connections exist between the components  
or
- the components/connections are more complex

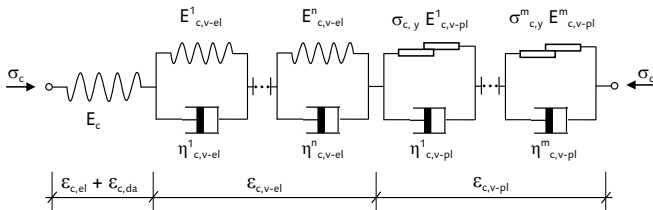
# Example: Rheological Creep Models



Kelvin element - low complexity



Poynting-Thompson element - medium complexity



Rheological creep model according to Heidolf - high complexity

# What is Uncertainty?

## Definition:

- Lack of complete certainty, when more than one possibility exists  
i.e. the **true** outcome/state is not known
- We use the term to describe our incomplete knowledge

## Where does it stem from?

Wherever our knowledge is incomplete!

- Science underlying a model
- Model parameters
- Input data
- Measured data (Observation error)
- Code uncertainty

# Sources of Uncertainty: A Categorization

## Model Framework Uncertainty

Uncertainty in the underlying science and algorithms

- Lack of knowledge about the behavior
- Simplifications

## Model Niche Uncertainty

Misapplication of the model

- Application of the model outside the expected system
- Combining models with different spatial/temporal scales

# Sources of Uncertainty: A Categorization

## Model Input Uncertainty

Resulting from:

- Data measurement errors
- Inconsistencies between measured and input data
- Parameter value uncertainty

They have different sources, i.e. either they arise from:

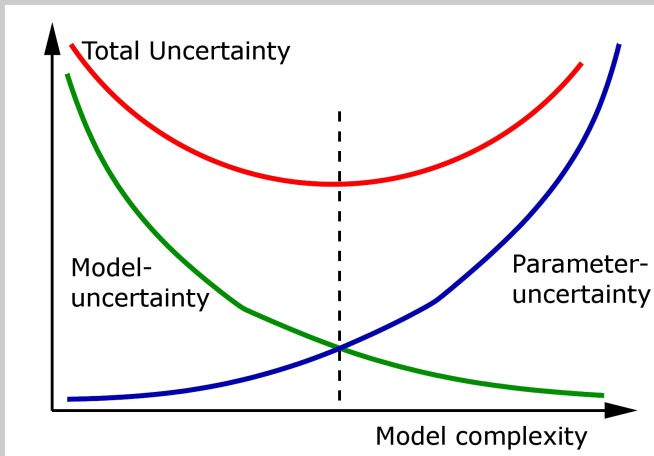
- Measurement errors
- Analytical imprecision
- Limited sample size

or

- Stochasticity / inherent randomness

# Uncertainty of model response

## Parameter- and model uncertainty



Uncertainty depending on model complexity

# Uncertainty: Final Remarks

## How to deal with uncertainty?

For a model response  $Y$

- Coefficient of variation  $CV_Y$
- Standard deviation  $\sigma_Y$

are used to quantify the uncertainty of the prediction

Model uncertainty allows for a deterministic interpretation as model error. **But...**

Parameter uncertainty can only be defined in the framework of stochastic analysis.

# Reliability

## Definition

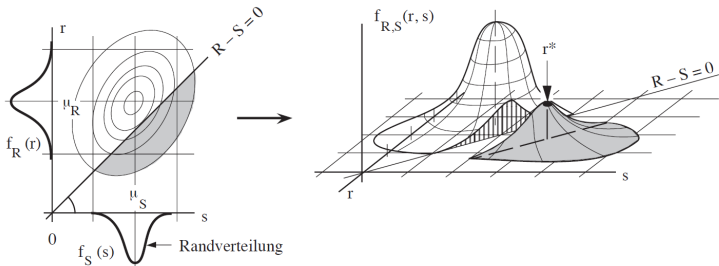
- Reliability denotes the probability that a response of structure does not exceed a certain failure limit within its "life-time" taking into account all uncertainties that influence the structural behavior

## Reliability ...

- ...is a probability - failure is regarded as a random phenomenon
- ...is predicated on "intended purpose", e.g. operation without failure
- ...applies to a specified period of time
- ...is restricted to operation under stated conditions



# Reliability $Z = P(S < R)$



[Bucher 2009]



[Schneider 1994]

# Sensitivity - Definitions [Saltelli et al. 2008]

## Goal

- Investigate influence of input parameters on model output
- Stochastic sense: Study of how the variation in the output can be apportioned to different sources of variation in the input

## Outcome and Benefit

- **Parameter fixing (PF)**: parameters with low sensitivity can be considered as deterministic - reduction of complexity
- **Parameter prioritization (PP)**: key model parameters are identified - become target of further investigations
- **Parameter mapping (PM)**: it is found out which parameter variation leads to an excess of a certain limit
- Help for the understanding of the model

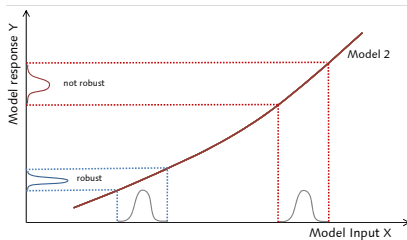
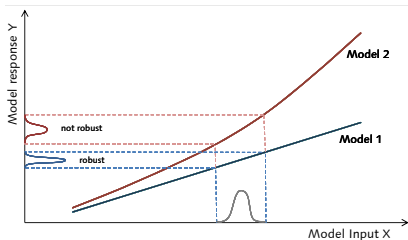


# Model Robustness

For example: Taguchi Robustness

$$T = 10 \cdot \log_{10} (\sigma_Y^{-2})$$

with:  $\sigma_Y$  - standard deviation of model response



# Risk in Structural Engineering

Most of the structural engineers think...

... that a structure is free of risk, if the design of all the structural members is done. But that is not right.

Risk...

... is the effect of uncertainty on objectives.

$$\text{risk} = \text{consequences} \times \text{probability}$$

$$R(x) = C(x) \times P(x)$$

- Consequences are often described by costs
- Decreasing risk leads to increasing construction costs

# Example for Risk

## Risk ...

... is the effect of uncertainty on objectives.

$$\text{risk} = \text{consequences} \times \text{probability}$$

## Risk is not ...

... that an earthquake occurs.

This is only a probability.

## Risk is ...

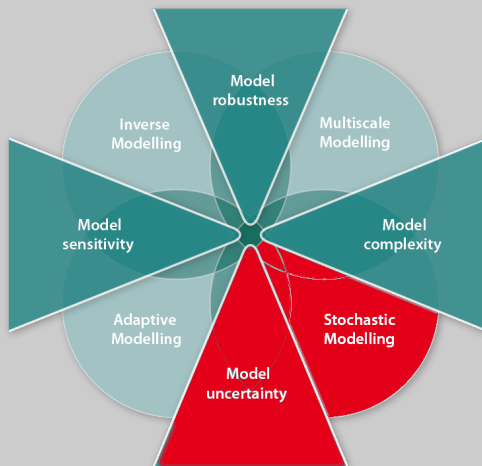
... that an earthquake occurs and you stay in a building which cannot resist the load and fails.

Then you have the probability of the earthquake and the consequences of the failure.

# Stochastic Modeling

Modeling technique: stochastic modeling

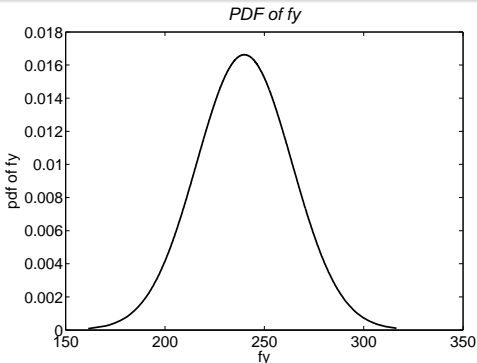
Criterion: model uncertainty



# Stochastic Modeling: Why?

The world is random, not deterministic

- Material parameters, loading, environmental parameters, and geometrical properties are uncertain input
- My model is not reality → it's uncertain





# Stochastic Modeling: Why?

## How does the randomness of input effect my output?

- Uncertain input leads to an uncertain output
- The degree of uncertainty of the prediction steers directly the belief in the model and the results

## What to do?

- Quantify the uncertainty of the model prediction
- Consider uncertainty in the evaluation of the design of structures

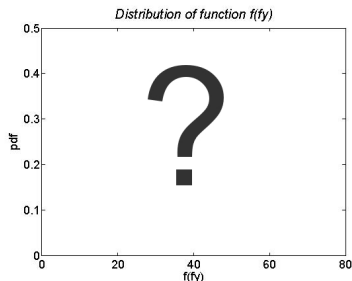
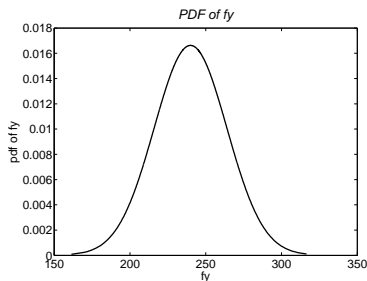
# Stochastic Modeling: How?

## Analytical solution

- Exist for well defined models or equations
- Are not applicable to numerical models, complex models etc.

## Monte Carlo simulation

- Numerical approximation of probability space
- **MC simulations are possible for all deterministic models**



# Monte Carlo

## Main idea

- Approximate continuous probability density function (PDF) with discrete samples from the PDF

$$\text{Continuous: } E[f(x)] = \int_{-\infty}^{\infty} f(x) p(f(x))$$

$$\text{MC: } \hat{E}[f(x)] = \frac{1}{N} \sum_{i=1}^N f(x)$$

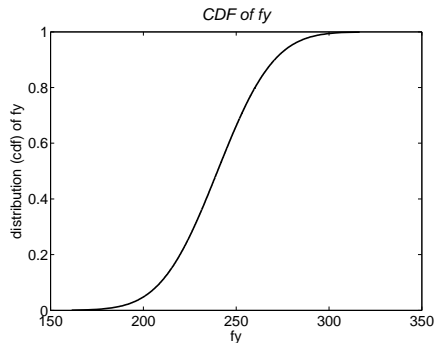
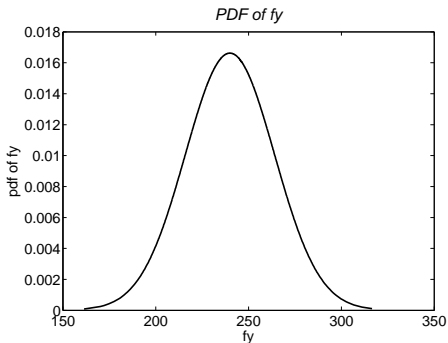
$$\text{MC: } \hat{\sigma}^2[f(x)] = \frac{1}{N} \sum_{i=1}^N \left( f(x) - \hat{E}[f(x)] \right)^2$$

$N$  is the number of total samples

$f(x)$  is a function depending on input  $x$

# Monte Carlo

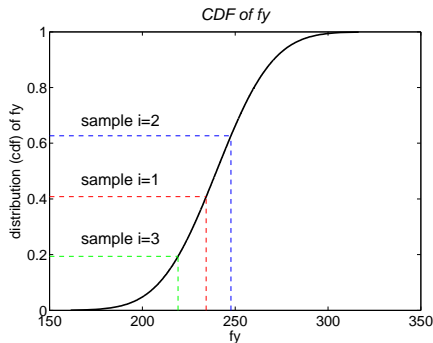
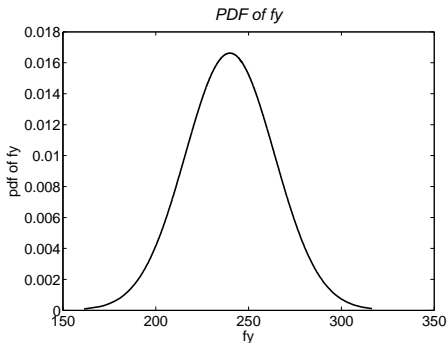
- Generate  $N$  random numbers (samples) between 0 and 1
- Numbers are equivalent to values of cumulative distribution function (CDF)
- Calculate parameter sample  $x^i$  using the inverse CDF



# Monte Carlo

Sample  $f_y$  from distribution  $\mathcal{N}(240, 24)$

sample	CDF <sup><i>i</i></sup>	$f_y^i$
1	0.41	234.4
2	0.63	247.8
3	0.19	219.3
...	...	...



# Parameter Results

sample	$CDF^i$	$fy^i$	$\hat{E}[fy]$	$\hat{\sigma}[fy]$	$\hat{\sigma}^2[fy]$
1	0.41	234.4			
2	0.63	247.8			
3	0.19	219.3	240.2	24.8	161.6
...	...	...			
100	0.94	278.2			

# Next Steps

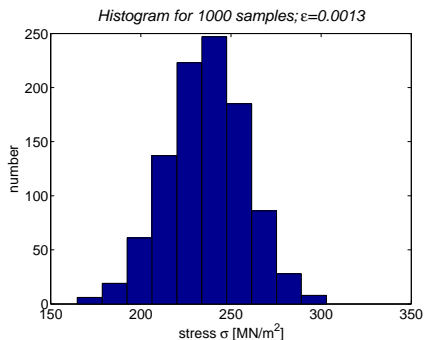
- Generate  $N$  samples for all stochastic input parameters
- If necessary, consider correlation
- Run model  $N$ -times for all parameter combinations
- Evaluate samples of model output
- Sufficient number of samples required to calculate reliable stochastic properties - might be computational expensive

# Model Results

- Model  $Y$  is calculated for 10 samples (usually too low!!!)
- Response values for  $\epsilon = 0.0013$ :

sample	$f_y^i$	$E^i$	$Y^i$
1	220	207600	220
2	222	252070	222
3	240	228160	239
4	287	201210	241
5	194	211400	194
6	231	193520	231
7	253	187360	225
8	258	177400	213
9	266	217430	266
10	242	223010	242

- Results:  $\hat{E}[Y] = 235$ ,  $\hat{\sigma}_{Y,par} = 21$ ,  
and  $\hat{\sigma}_{Y,par}^2 = 439$

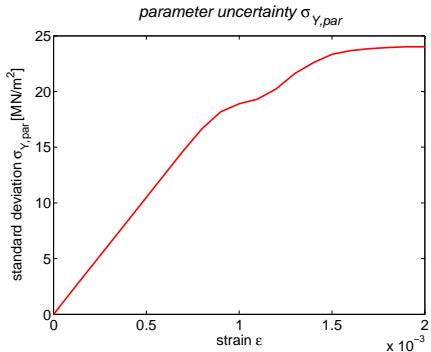
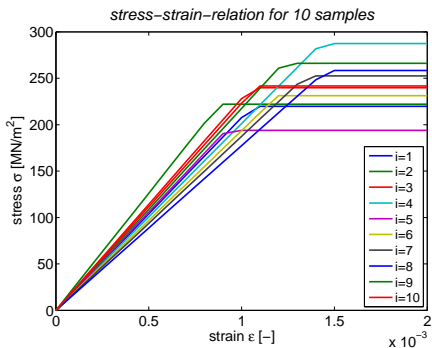




# Model Results

- Evaluate scatter of response
- Measures: standard deviation  $\sigma_Y$  or coefficient of variation

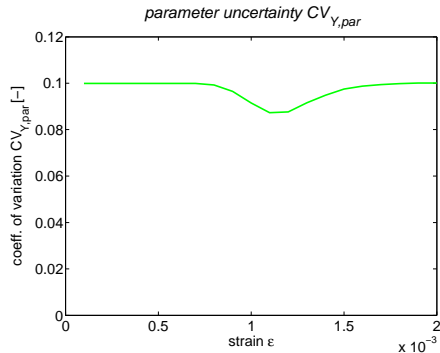
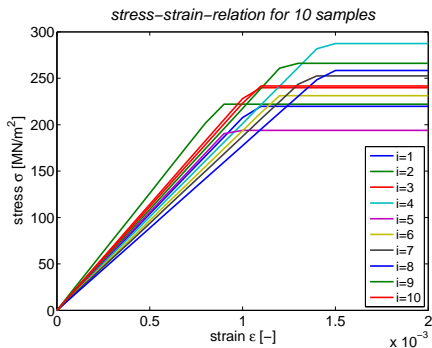
$$CV = \frac{\sigma_Y}{E[Y]}$$



# Model Results

- Evaluate scatter of response
- Measures: standard deviation  $\sigma_Y$  or coefficient of variation

$$CV = \frac{\sigma_Y}{E[Y]}$$



# Adding Model Uncertainty

## Model Uncertainty

- Represents general error/misprediction of model
- Expressed by standard deviation  $\sigma_{mod}$  or  $CV_{mod}$
- Increases total uncertainty of prediction
- Parameter and model uncertainty are combined by summation of the variances or CV's
$$\sigma_{Y,tot}^2 = \sigma_{Y,par}^2 + \sigma_{Y,mod}^2 \quad \text{and} \quad CV_{Y,tot}^2 = CV_{Y,par}^2 + CV_{Y,mod}^2$$
- Total uncertainty can be used to evaluate models

# Model Quality

## Model Quality

- Model quality of model  $j$  can be directly related to the CV of the prediction

$$MQ_j = \frac{\min CV_Y}{CV_{Y,j}}$$

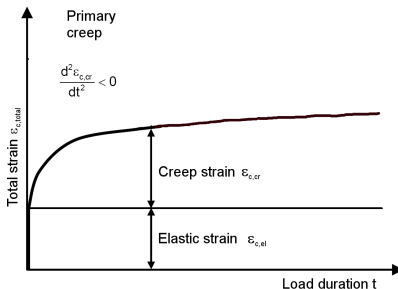
- Low uncertainty  $\rightarrow$  good quality
- High uncertainty  $\rightarrow$  poor quality

## In general...

- More complex models have more uncertain (hard to identify) parameters  $\rightarrow$  higher parameter uncertainty
- More complex models capture real behavior better  $\rightarrow$  less model uncertainty
- Evaluation find the best compromise

# Application to Concrete Creep Models

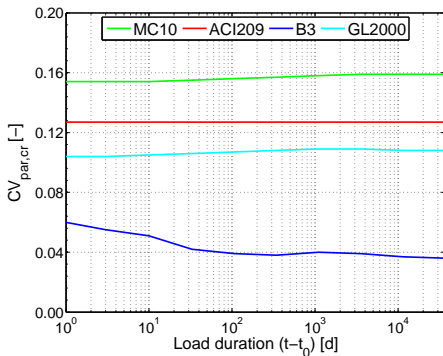
- Concrete creep models describe time-dependent increase in compliance/deformation suspected to sustained loading
- Many different approaches available
- Creep phenomenon not totally understood → high uncertainty in prediction



Characteristic time-dependent strains of concrete

# Parameter Uncertainty

- Assignment of stochastic distribution of inputs considering correlation, e.g. Young's modulus and concrete strength
- Monte Carlo analysis using Latin Hypercube Sampling
- Resulting parameter uncertainty can be time-dependent



Time-dependent parameter uncertainty

# Creep Model Uncertainty

- Estimation of uncertainty  $CV_{Z,cr}$  from comparison of model prediction to many different measurements
- Decomposition of uncertainty [Madsen & Bažant 1983]

$$CV_{Z,cr}^2 = CV_{mod,cr}^2 + CV_{\varepsilon}^2 + CV_{\alpha}^2$$

with:	uncertainty of creep model	$CV_{mod,cr}$
	measurement uncertainty	$CV_{\varepsilon} \approx 0,05$
	uncertainty of creep phenomenon	$CV_{\alpha} \approx 0,08$

- Creep model uncertainty

$$CV_{mod,cr} = \sqrt{CV_{Z,cr}^2 - CV_{\varepsilon}^2 - CV_{\alpha}^2}$$

# Model Uncertainty in MC Simulations

## Definition of model uncertainty factor $\Psi_{mod,cr}$

- Normal distribution of  $\Psi_{mod,cr}$ , mean value  $\bar{\Psi}_{mod,cr} = 1$
- $CV_{Z,cr}$  of models based on RILEM databank [Bažant & Li 2008]

model	$CV_{Z,cr}$	$CV_{mod,cr}$
MC10	0,31	0,29
ACI209	0,39	0,37
B3	0,28	0,27
GL2000	0,28	0,27

- Model uncertainty constant in time [Gardner 2004]
- Multiplication with calculated creep compliance

$$C_{mod,cr}(t) = \Psi_{mod,cr} C_c(t)$$



# Model Quality

- Total uncertainty

$$CV_{tot,cr}(t) = \sqrt{CV_{par,cr}^2(t) + CV_{mod,cr}^2}$$

- Time-dependent quality of model  $j$

$$MQ_{cr,j}(t) = \frac{\min(CV_{tot,cr}(t))}{CV_{tot,cr,j}(t)}$$

- Total model quality

$$MQ_{cr} = c \sum_{i=1}^N \frac{MQ_{cr}(t_i, t_0) + MQ_{cr}(t_{i+1}, t_0)}{2} [\log(t_{i+1} - t_0) - \log(t_i - t_0)]$$

with:  $c$  normalization constant  
 $t_0, t_i$  and  $t_{i+1}$  time at loading, begin/end of time increment

# Example: Concrete C30/37

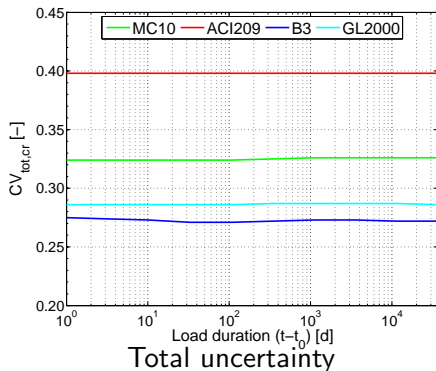
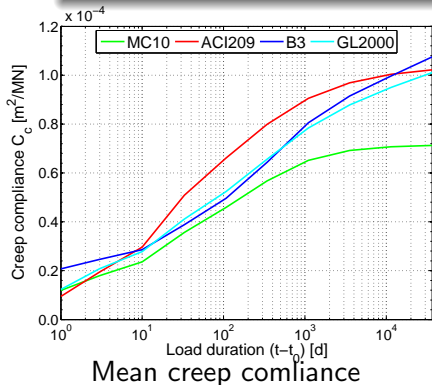
C30/37,  $t_0 = 28$  d,  $t_d = 7$  d,  $V/S = 0,05$  m  
stochastic input parameters

parameter	E	CV	distribution
$RH$	65 %	0.04	normal
$f_{c,28}$	38 MN/m <sup>2</sup>	0.06	log-normal
$E_{c0,28}$	31900 MN/m <sup>2</sup>	0.10	log-normal
$E_{cm,28}$	27150 MN/m <sup>2</sup>	0.15	log-normal
$c$	362 kg/m <sup>3</sup>	0.10	normal
w-c	0.47	0.10	normal
a-c	5.16	0.10	normal
f-a	0.5	0.10	normal
sl	38 cm	0.10	normal
a	0.015	0.20	normal
$k_s$	1.15	0.05	normal

# Example: Concrete C30/37

## Results of stochastic analysis

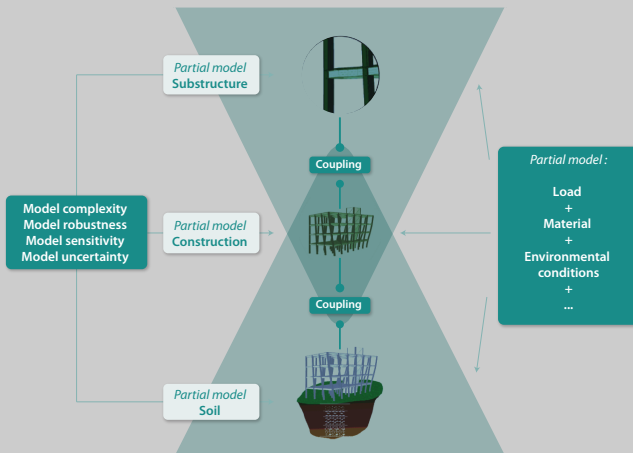
- Different mean creep compliance  $C_c(t)$
- Large differences of the uncertainty of the prediction
- Low time-dependency of uncertainty





# Evaluation of Coupled Partial Models

## Evaluation of individual partial models is done - what's next?



# Evaluation of Coupled Partial Models

Evaluation of individual partial models is done - what's next?

- How to combine the individual qualities?
- When combining PMs, are there interaction effects present?
- What is the influence of coupling types on the prediction of the global model?

# Evaluation Method for Coupled PM's

- Evaluation based on graph theory
- Consideration of individual qualities of PMs
- Consideration of influence of PM on global model response
- 2-step procedure
  - ① Identify influence of class of PM
  - ② Identify influence of quality (model choice) on output
- Based on sensitivity studies
- Assumption so far: perfect coupling

# Variance-Based Global Sensitivity Analysis

## Sensitivity indices to quantify influence

- First order index  $S_i$ : exclusive influence of parameter  $X_i$

[Sobol 1993]

$$S_i = \frac{V(E(Y|X_i))}{V(Y)} = 1 - \frac{E(V(Y|X_i))}{V(Y)}$$

- Total effects index  $S_{Ti}$ : influence of parameter  $X_i$  including interactions with all other parameter  $\mathbf{X}_{\sim i}$  [Homma et al. 1996]

$$S_{Ti} = 1 - \frac{V(E(Y|\mathbf{X}_{\sim i}))}{V(Y)} = \frac{E(V(Y|\mathbf{X}_{\sim i}))}{V(Y)}$$

- Difference  $S_{Ti} - S_i$  is measure for interactions of input parameters



# Influence of Partial Model

## Method Step ①

- Each PM  $i$  is represented by an discrete random variable  $X_i$ ,  $i = 1, 2, 3$

$$X_i = \begin{cases} 0 & \text{PM non activated} \\ 1 & \text{PM activated} \end{cases}$$

- Sampling uncorrelated, uniformly distributed parameters  $X_i$
- Sensitivity analysis by *Saltelli*
- Determine the influence of PM by sensitivity indices  $S_i$  and  $S_{Ti}$
- Difference between  $S_i$  (First Order Effects) and  $S_{Ti}$  (Total Effects) indicates the effect of coupled partial model

# Influence of Partial Model Quality

## Method Step ②

- Random variable control the model selection in each PM

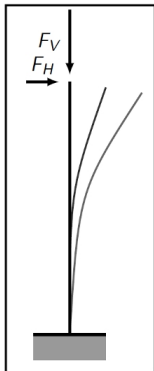
$$X_{geomNL} = \begin{cases} 1 & \text{P-}\Delta \\ 2 & \text{Geom. nonlinear} \end{cases}$$

- Sensitivity index  $S_{Ti,Ms}$  represent the influence of the model selection  $\Rightarrow$  High Index = quality of the PM is important

- Model quality:  $MQ_{GM} = \frac{\mathbf{S}_{Ti,Ms}^T \times \mathbf{MQ}_{PM}}{\Sigma S_{Ti,Ms}}$

# Global Quality of Bridge Model

geom. non-  
linearity

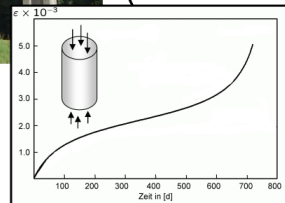


load model -  
traffic loading

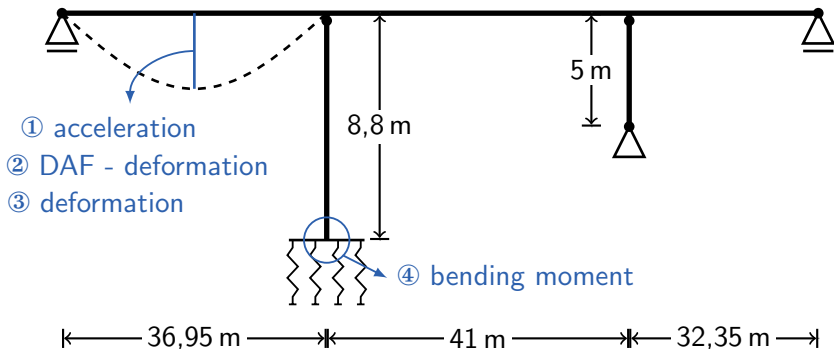


concrete -  
creep,  
shrinkage

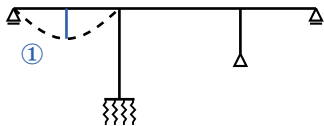
soil  
model



# Structure - Target Values



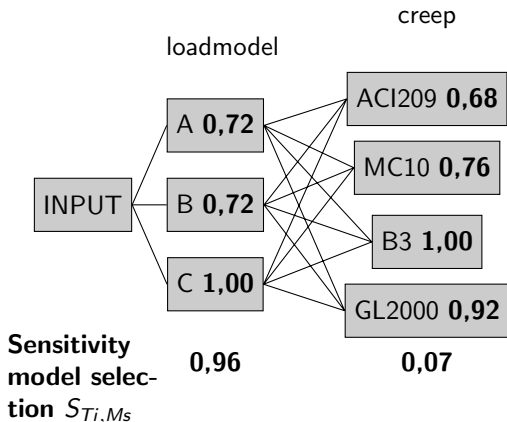
# Target Value: ① Acceleration



Sensitivity of class of partial model:

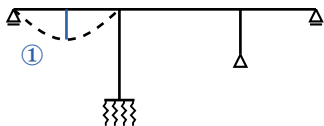
	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,02	0,03
shrinkage	0,00	0,00
soil	0,00	0,00
dyn. load	0,97	0,98

Quality structural model:



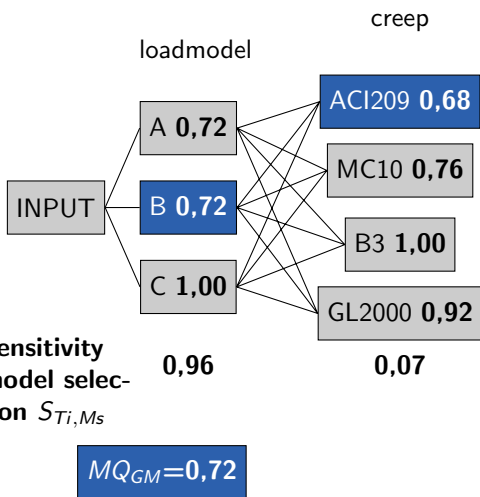
# Target Value: ① Acceleration

Quality structural model:

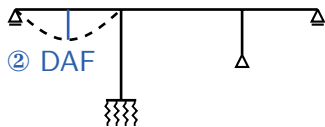


Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,02	0,03
shrinkage	0,00	0,00
soil	0,00	0,00
dyn. load	0,97	0,98



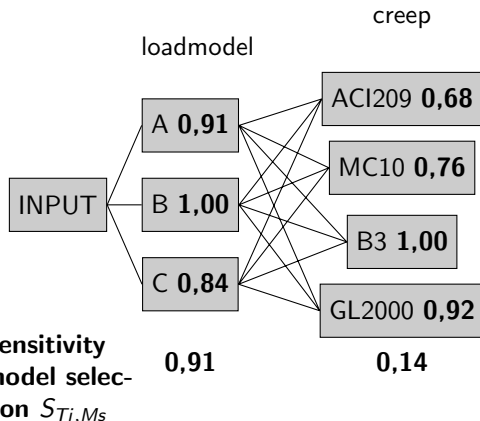
# Target Value: ② DAF - Deformation



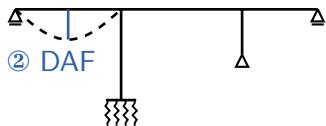
Quality structural model:

Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,03	0,06
shrinkage	0,00	0,00
soil	0,00	0,00
dyn. load	0,94	0,97



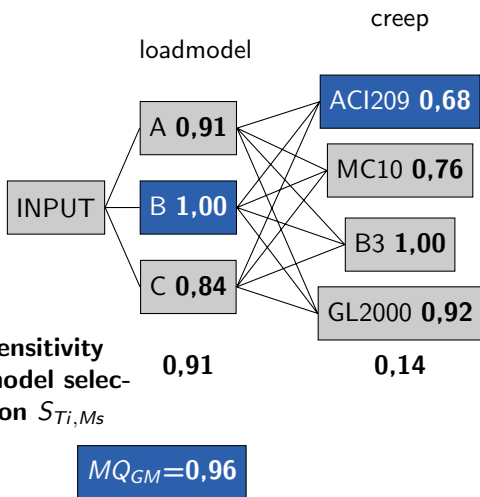
# Target Value: ② DAF - Deformation



Quality structural model:

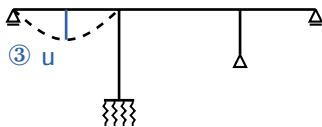
Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,03	0,06
shrinkage	0,00	0,00
soil	0,00	0,00
dyn. load	0,94	0,97





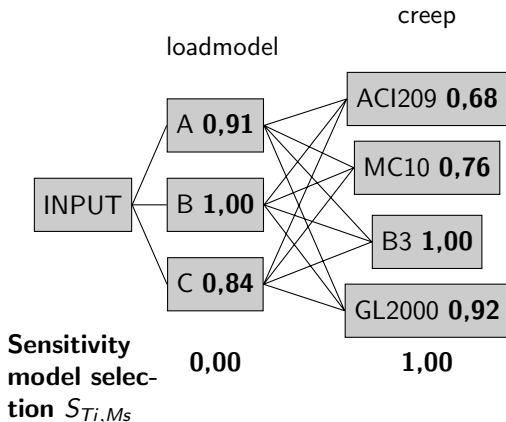
# Target value: ③ Field Deformation



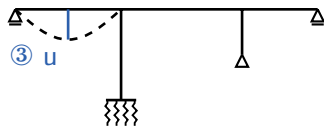
Quality structural model:

Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,98	0,98
shrinkage	0,01	0,01
soil	0,01	0,01
dyn. load	0,00	0,00



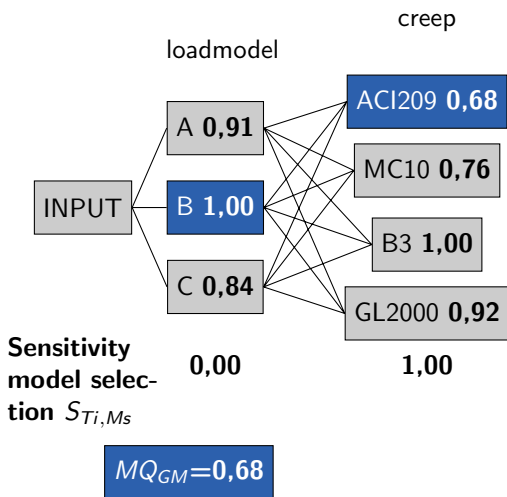
# Target value: ③ Field Deformation



Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,00	0,00
creep	0,98	0,98
shrinkage	0,01	0,01
soil	0,01	0,01
dyn. load	0,00	0,00

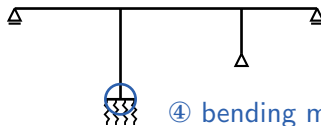
Quality structural model:



# Target Value: ④ Bending Moment

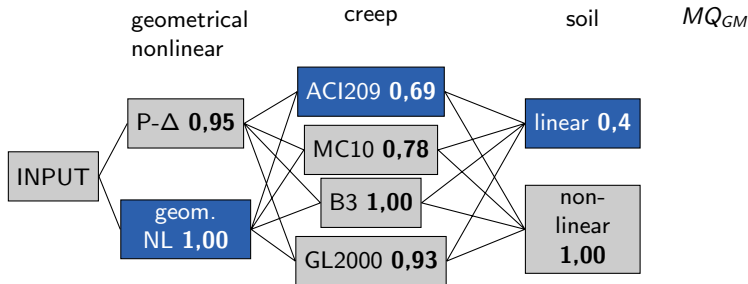
Sensitivity of class of partial model:

	$S_i$	$S_{Ti}$
geom. NL	0,89	0,94
creep	0,04	0,08
shrinkage	0,00	0,00
soil	0,00	0,01
dyn. load	0,02	0,02



# Target Value: ④ Bending Moment

Quality structural model:



Sensitivity  $S_{Ti, Ms}$   
for yield strength  
600 kN/m<sup>2</sup>

0,07

0,93

0,00

0,71

Sensitivity  $S_{Ti, Ms}$   
for yield strength  
500 kN/m<sup>2</sup>

0,02

0,05

0,95

0,43

# Summary of the method

- Model quality of global model is determined
- Coupling effects are detected and quantified
- Best model combination gets quality  $MQ_{GM}=1.0$ ; Difference to 1 is loss of quality
- Evaluation is performed for single response quantities, no generalization possible
- Results depend on load level

# Conclusions

- Many different possibilities are available to quantify prediction quality of PM
- Which method to use depends on characteristics of PM
- Stochastic evaluation is promising and flexible
- Challenging task is to determine model error/uncertainty without using specific measurements
- Often time-consuming evaluation process
- Quantifying influence of PM on global model helps to understand behavior and save evaluation time
- Generalization of results often difficult

# Reality - Model

